

Mengyi Zhou

✉ m.zhou23@imperial.ac.uk  github.com/x-Arte  [mengyi-zhou](https://www.linkedin.com/in/mengyi-zhou)

EDUCATION

Imperial College London <i>Master of Research (MRes) in Medical Robotics and Image-Guided Intervention</i> Average score (currently): 70.07/100 (3.9/4.0)	09/2023 - 09/2024
Beijing Normal University <i>Bachelor of Science (BSc) in Computer Science and Technology</i> Average score: 87.66/100 (3.7/4.0)	09/2019 - 06/2023

WORKING PAPERS

[1] **Mengyi Zhou**, Chi Xu, Stamatia Giannarou. Microscopic Visual Servoin for Robot-assisted Endomicroscopy Tissue Scanning. (**In Progress**)

ACADEMIC EXPERIENCES

Federated Learning Diffusion <i>Supervisor: Prof. Bo Zhou Northwestern University</i> <ul style="list-style-type: none">Project Overview: Developing a diffusion-based medical image translation system aimed at securely transferring data between different datasets using federated learning to ensure privacy.Conducted an extensive literature review to evaluate the strengths and limitations of previous generative models.Ongoing Work: Currently working on a generalized denoising and translation model based on Diffusion that obviates the need for specialized noise type specifications, thus improving model adaptability and general applicability.	06/2024 - Present <i>Remote</i>
Microscopic Visual Servoing for Robot-assisted Endomicroscopy Tissue Scanning <i>Supervisor: Prof. Stamatia Giannarou, Chi Xu Imperial College London</i> <ul style="list-style-type: none">Project Overview: Developed a deep learning-based system to guide robot-assisted endomicroscopy, particularly focusing on tissue scanning using probe-based confocal laser endomicroscopy (pCLE).Extended single-image distance regression to video-based regression using temporal information from pCLE videos, improving accuracy and stability.Developed a trajectory planning algorithm that optimized probe paths, resulting in a 26% improvement in probe fluctuation distance accuracy.Outcome: One paper in progress. Poster presentation at the 16th Hamlyn Symposium on Medical Robotics, June 25, 2024.	02/2024 - Present <i>London, UK</i>
Development of a Multi-sensing Optical Probe for Tumour Margin Mapping <i>Supervisor: Prof. Alex Thompson, Prof. Stamatia Giannarou Imperial College London</i> <ul style="list-style-type: none">Project Overview: Developed a multi-sensing system to facilitate real-time, accurate tumor margin mapping by combining confocal endomicroscopy images with Raman spectra.Achieved 99.3% accuracy in tumor classification by developing a VGG19-based classifier for pCLE images.Integrated Raman spectral classification with pre-trained models and PCA-based techniques, resulting in a 20% accuracy improvement over traditional Raman-only methods.Outcome: Developed a robust multimodal classification model with enhanced accuracy through fusion of visual and spectral data..	10/2023 - 12/2023 <i>London, UK</i>
Classification of Eclipsing Binary Light Curves Based on Deep Learning <i>Supervisor: Prof. Xianchuan Yu Beijing Normal University</i> <ul style="list-style-type: none">Project Overview: Implemented a deep learning model to classify eclipsing binary light curves, contributing to the analysis of astronomical data.Applied periodogram methods to estimate non-equally spaced time series periods and smoothed light curve data using Linear Interpolation for classification.Developed an auto-encoder model based on LSTM for unsupervised feature extraction, achieving a classification accuracy of 90%.Outcome: This research formed the basis of my Undergraduate Graduation Thesis.	12/2022 - 05/2023 <i>Beijing, China</i>

PROJECT EXPERIENCES

SpacToolChain Game Visualization Development Toolset	05/2024 - Present
<i>Core Member, Back-End developer</i>	
<ul style="list-style-type: none">• Introduction: Contributing to the development of an automated toolset designed to streamline game content creation by separating front-end and back-end operations, utilizing Vue.js 3 for the front-end and Flask for the back-end. This toolset is intended for internal use within a game development project.• Developed and implemented a node-based data storage management system using Flask, enabling efficient handling of game-related data and assets.• Integrated a personnel rights management system to facilitate role-based access control within the toolset, ensuring secure and controlled content creation workflows.• Ongoing Development: Currently working on gameplay development features in Unity, focusing on core mechanics such as action logic, an equipment system, and its effects on combat.• Current Outcome: A web-based interface for managing game content, including non-player characters (NPCs), dialogues, and other in-game assets. The system is actively used in game development to streamline content creation and personnel management.	

AWARDS

Outstanding Undergraduate Graduation Thesis	2023
Mathematical Contest in Modeling (MCM) - Finalist (Top 2%)	2022
Scholarship for Competition Participation - First-Class	2022
Scholarship for Academic - Third-Class (twice)	2021 - 2022

EXTRACURRICULAR ACTIVITIES

“EnviroMoment” Environmental Education Innovation and Communication	2021 - 2022
Beijing Normal University Cycling Association - Vice President	2021 - 2022
Beijing Normal University Volunteer Teacher Team - Publicity Vice Director	2021

SKILLS

Programming: Python (PyTorch, TensorFlow, SKLearn, Flask, etc.), C/C++, MATLAB, Java, SQL
Modeling and Multimedia Softwares: Unreal Engine 4, Unity, Blender, PS, PR, AU
Language: Chinese (native), English (IELTS-7.0)